

# A Note on Optimal Algorithms for Fixed Points

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## Abstract

We present a constructive lemma that we believe will make possible the design of nearly optimal  $O(d \log \frac{1}{\epsilon})$  cost algorithms for computing  $\epsilon$ -residual approximations to the fixed points of  $d$ -dimensional nonexpansive mappings with respect to the infinity norm. This lemma is a generalization of a two-dimensional result that we proved in [1].

## 1 Introduction

In [1, 2] we presented two-dimensional optimal complexity algorithms for computing residual  $\epsilon$ -approximations to the fixed points of non-expansive mappings with respect to the infinity norm. These algorithms are based on bisection-envelope constructions and are derived from Theorem 3.1 of [1]. This theorem makes possible construction of a sequence of rectangles that contain fixed points and converge to the residual  $\epsilon$ -approximation of some fixed point. At every iteration of the process the previous rectangle is cut by a factor of at least two, to obtain a new rectangle containing a fixed point.

In this paper we generalize the constructive theorem to an arbitrary number of dimensions  $d \geq 3$ , however, we are unable to utilize this new result in the construction of optimal algorithms.

The main obstacle in such construction is the ability to bound a new set containing fixed points by an “easy-to-construct” convex set of smaller volume and similar topological features to the previous set in this process. We stress that the two-dimensional sets in the optimal algorithm are rotated rectangles. What would be the proper sets in an arbitrary number of dimensions that would bound the non-convex sets resulting from the application of our general  $d$ -dimensional lemma?

## 2 Problem formulation

Given dimension  $d \geq 2$ , we define  $D = [0, 1]^d$  and the class  $F$  of functions,  $f : D \rightarrow D$ , that are Lipschitz continuous with constant 1 with respect to the

infinity norm, i.e.,

$$\|f(x) - f(y)\| \leq \|x - y\|, \forall x, y \in D$$

where  $\|\cdot\| = \|\cdot\|_\infty$  henceforth. We seek an algorithm which, for every  $f \in F$ , computes a solution  $\tilde{x} = \tilde{x}(f) \in D$  that satisfies the residual criterion

$$\|f(\tilde{x}) - \tilde{x}\| \leq \epsilon \tag{1}$$

where  $0 < \epsilon < 0.5$ . (If  $\epsilon \geq 0.5$  then  $x = (0.5, 0.5)$  satisfies [1]). The algorithm requires  $n(f)$  function evaluations, where  $n(f) \cong O(d \log \frac{1}{\epsilon})$ . In the case of  $d = 2$  the algorithm is based on Theorem 3.1 of [1], utilizes bisection of rectangles and envelope constructions, and has cost  $2 \log_2 \frac{1}{\epsilon}$ . Here we present a generalization of this theorem to the case of  $d \geq 3$ . We believe that the general result will provide the basis for construction of a future algorithm having the desired efficiency. So far we have been unable to construct such an algorithm. We stress that computing  $x_\epsilon, \|x_\epsilon - \alpha\| \leq \epsilon$ , an  $\epsilon$ -absolute approximation to the fixed point  $\alpha$ , in the class of expanding functions is of infinite complexity in the worst case [3].

### 3 Definitions

For a given  $f \in F$  and  $i = 1, \dots, d$  we define the fixed point sets  $F_i$  such that for each  $i$ ,

$$F_i(f) = \{x \in D : f_i(x) = x_i\}.$$

We define  $F(f) = \cap_{i=1}^d F_i(f)$ , the nonempty set of all fixed points of  $f$ . For all  $x \in \mathbb{R}^d$ ,  $i = 1, \dots, d$ , and  $s \in \{-1, 1\}$  we define the ‘‘open-ended’’ pyramid sets

$$A_i^s(x) = \{y \in \mathbb{R}^d : \|y - x\| = s(y_i - x_i)\}.$$

For all  $x \in \mathbb{R}^d$ ,  $i = 1, \dots, d$ ,  $s \in \{-1, 1\}$ , and  $c > 0$ , we also define the ‘‘flat-top’’ pyramid set

$$Q_i^s(x, c) = \cup \{A_i^s(y) : y \in \mathbb{R}^d, \|y - x\| < c\}.$$

### 4 Constructive Lemma

In this section we prove our constructive lemma. It is a generalization of Theorem 3.1 of [1] to an arbitrary number of dimensions  $d \geq 3$ .

#### Lemma 4.1

For any  $f \in F$ ,  $i = 1, \dots, d$ , we let  $x \in D$  be such that  $f_i(x) \neq x_i$ . Then the following holds:

- (i) If  $f_i(x) > x_i$  then  $Q_i^{-1}(x, (f_i(x) - x_i)/2) \cap D \cap F_i(f) = \emptyset$ .

(ii) If  $f_i(x) < x_i$  then  $Q_i^1(x, (x_i - f_i(x))/2) \cap D \cap F_i(f) = \emptyset$ .

*Proof.* To show (i) we take any  $y$  such that  $\|y - x\| < (f_i(x) - x_i)/2$ , and  $z \in A_i^{-1}(y) \cap D$ . Then

$$|f_i(z) - f_i(y)| \leq \|f(z) - f(y)\| \leq \|z - y\| = y_i - z_i$$

and

$$\begin{aligned} f_i(y) - y_i &= f_i(x) - (f_i(x) - f_i(y)) - x_i - (y_i - x_i) \geq f_i(x) - x_i - 2\|y - x\| \\ &> f_i(x) - x_i - (f_i(x) - x_i) = 0, \end{aligned}$$

which implies

$$f_i(z) = f_i(y) + (f_i(z) - f_i(y)) > y_i - (y_i - z_i) = z_i.$$

To show (ii) we take any  $y$  such that  $\|y - x\| < (x_i - f(x_i))/2$ , and  $z \in A_i^1(y) \cap D$ . Then

$$|f_i(z) - f_i(y)| \leq \|f(z) - f(y)\| \leq \|z - y\| = z_i - y_i$$

and

$$\begin{aligned} f_i(y) - y_i &= f_i(x) + (f_i(y) - f_i(x)) - x_i + (x_i - y_i) \leq f_i(x) - x_i + 2\|y - x\| \\ &< f_i(x) - x_i + (x_i - f_i(x)) = 0, \end{aligned}$$

which implies

$$f_i(z) = f_i(y) + (f_i(z) - f_i(y)) < y_i + (z_i - y_i) = z_i. \quad \blacksquare$$

## Comments

The above Lemma 4.1 states that after evaluating  $f$  at  $x$  we can remove from the original domain  $D$  the “flat-top” pyramid sets  $Q_i^s(x, c_i)$  for all  $i$  such that  $c_i = |f(x_i) - x_i|/2$  are not zero, since they do *not* contain fixed points of  $f_i$ , implying that they do not contain any fixed point of  $f$  as well. If this happens for all  $i = 1, \dots, d$  then we can reduce the volume of the set containing fixed points by a factor of at least two.

## Open problems

The main obstacle in constructing a recursive algorithm (for  $d \geq 3$ ) based on Lemma 4.1 is our apparent inability to construct a sequence of sets  $S_j$  that each contain a fixed point, are topologically “similar”, decrease in volume, and are easy to represent, and then evaluating  $f$  at the “centers” of  $S_j$ . Also, it needs to be decided which sets can be removed from  $S_j$  in the case where  $f_i(x) - x_i = 0$ , i.e., when the current evaluation point  $x$  is a fixed point of some components of  $f$ .

We believe that by solving those problems we can obtain an optimal  $O(d \log \frac{1}{\epsilon})$  cost algorithm for finding  $\epsilon$ -residual solutions to the fixed points of functions in our class. We hope to address these issues in a future paper.

## References

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