

Fo D A , Gradient L 1 7 Descent * Fitting Models to Data

data set $(X, y) = \{(x_1, y_1), (x_2, y_2), \dots (x_n, y_n)\} \subset \mathbb{R}^d \times \mathbb{R}$

Goal: Model M_α

$$\alpha = (\alpha_1, \dots, \alpha_k)$$

minimize loss function

$$f(\alpha) = L((X, y), M_\alpha)$$

$$f(\alpha): \mathbb{R}^k \rightarrow \mathbb{R}$$

$$= SSE((X, y), M_\alpha) = \sum_{\substack{(x_i, y_i) \\ \in (X, y)}} (y_i - M_\alpha(x_i))^2$$

$$(x_i, y_i) \quad x \in \mathbb{R}^n \quad y \in \mathbb{R}^n$$

$$(x_i, y_i) \in \mathbb{R} \times \mathbb{R}$$

model
quadratic

$$\begin{aligned} M_\alpha(x_i) &= \langle \alpha, (1, x_i, x_i^2) \rangle \\ &= \alpha_0 + \alpha_1 x_i + \alpha_2 x_i^2 \end{aligned}$$

Gradient Descent

$$f(\alpha) = \sum_{i=1}^n (M_\alpha(x_i) - y_i)^2$$

$$\alpha = \alpha - \gamma \nabla f(\alpha)$$

Single Data Point $(x_{i,y})^{\boxed{n=1}} = (x_i, y_i)$

$$f(\alpha) = f_1(\alpha) = (\alpha_0 + \alpha_1 x_1 + \alpha_2 x_1^2 - y_i)^2$$

convex in α

$$\nabla f(\alpha) = \left(\frac{\partial}{\partial \alpha_0} f(\alpha), \frac{\partial}{\partial \alpha_1} f(\alpha), \frac{\partial}{\partial \alpha_2} f(\alpha) \right)$$

$$\frac{\partial}{\partial \alpha_j} f(\alpha) = \frac{\partial}{\partial \alpha_j} (M_\alpha(x_i) - y_i)^2$$

$$= \sum (M_\alpha(x_i) - y_i) \frac{\partial}{\partial \alpha_j} (M_\alpha(x_i) - y_i)$$

$$= \sum (M_\alpha(x_i) - y_i) \frac{\partial}{\partial \alpha_j} \left(\sum_{i=0}^2 \alpha_i x_i^i - y_i \right)$$

$$= \sum (M_\alpha(x_i) - y_i) x_i^j$$

LMS update rule

Widrow-Hoff learning rule

$$\nabla f(\alpha) = \left(\frac{\partial}{\partial \alpha_0} f(\alpha), \frac{\partial}{\partial \alpha_1} f(\alpha), \frac{\partial}{\partial \alpha_2} f(\alpha) \right) = \sum (M_\alpha(x_i) - y_i) (1, x_i, x_i^2)$$

Decomposable Functions

(n > 1) Data Points

$$f(\alpha) = \sum_{i=1}^n f_i(\alpha)$$

$$f_i(\alpha) = (M_\alpha(x_i) - y_i)^2$$

$$f(\alpha) = \sum_{i=1}^n f_i(\alpha) = SSE((x_i), M_\alpha)$$

Batch Gradient Descent

$$\nabla f(\alpha) = \sum_{i=1}^n \nabla f_i(\alpha) = \left(\sum_{i=1}^n \frac{\partial}{\partial \alpha_0} f_i(\alpha), \dots, \sum_{i=1}^n \frac{\partial}{\partial \alpha_k} f_i(\alpha) \right)$$

$$\text{LMS Update} = \sum_{i=1}^n z(M_\alpha(x_i) - y_i) (1, x_i, x_i^2, \dots)$$

LMS Update

$$f(\alpha) = \sum_{i=1}^n \left(\alpha_0 + \alpha_1 x_i + \alpha_2 x_i^2 - y_i \right)^2$$
$$= \sum_{i=1}^n f_i(\alpha)$$

LMS
Update

$$\nabla f_i(\alpha) = 2 \left(\alpha_0 + \alpha_1 x_i + \alpha_2 x_i^2 - y_i \right) \cdot (1, x_i, x_i^2)$$

$$\nabla f(\alpha) = \sum_{i=1}^n 2 \left(\alpha_0 + \alpha_1 x_i + \alpha_2 x_i^2 - y_i \right) \text{Residual } (\alpha(x_i) - y_i) (1, x_i, x_i^2)$$

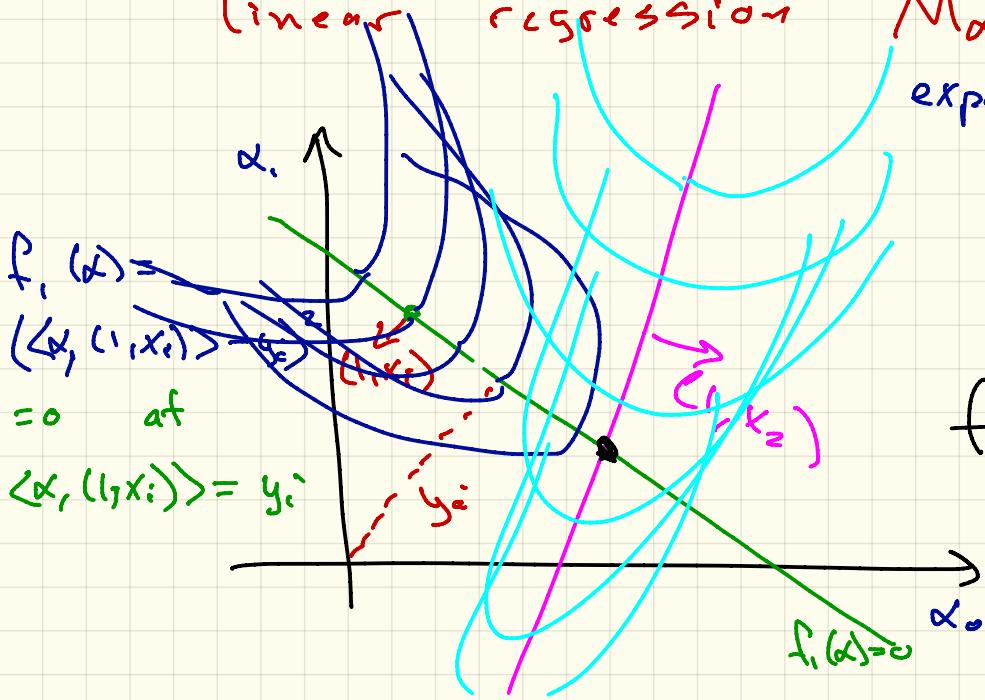
expanded
explanatory
data point
 $x_i \rightarrow (1, x_i, x_i^2)$

Since $f_i(\alpha)$ convex

$\rightarrow \sum_{i=1}^n f_i(\alpha)$ convex

strongly convex?

linear regression



$$f(\alpha) = f_1(\alpha) + f_2(\alpha)$$

expander $x_i \rightarrow (1, x_i) \in \mathbb{R}^2$
model $\alpha = (\alpha_0, \alpha_1)$

$$f(\alpha) = f_1(\alpha) + f_2(\alpha)$$

strongly convex

if $\begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ \vdots & \vdots & \vdots \end{bmatrix}$ full rank

What about Big Data?

Calculating $\nabla f(\alpha) = \sum_{\epsilon=1}^n \nabla f(\alpha)$
take $\mathcal{O}(n)$

approximate $\nabla f(\alpha)$ in constant time

$$\nabla f_i(\alpha) = z(M_\alpha(x_i) - y_i) (1, x_i, x_i^2) \\ (x_i, y_i)$$

Incremental Gradient Descent

D. Initialize $\alpha^{(0)} \in \mathbb{R}^d$, $i=1$, $f_2=0$

1. repeat

$$\alpha^{(t+1)} = \alpha^{(t)} - \gamma \nabla f_i(x^{(t)})$$

maybe make smaller than full GD
Grad at 1 data point.

2. Until $i \equiv (i+1) \pmod n$

take sliding average over B step

Stochastic Gradient Descent (SGD)

0. $\alpha^{(0)} = \alpha \in \mathbb{R}^d$

1. repeat

a. Randomly choose $i \in \{1, 2, \dots, n\}$

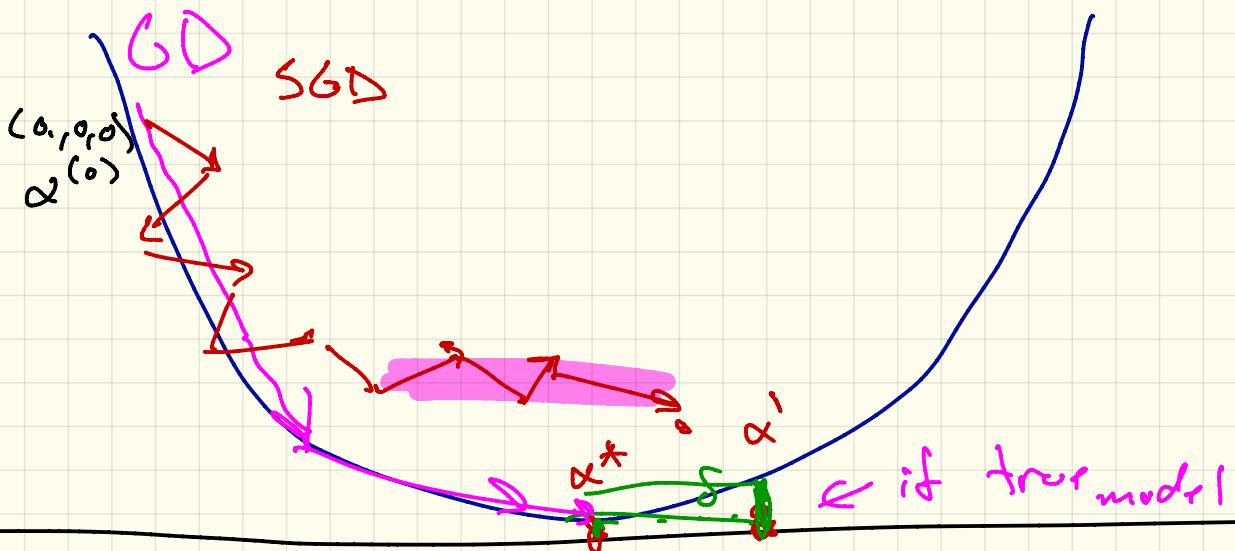
b. $\alpha^{(k+1)} = \alpha^{(k)} - \gamma \nabla f_i(\alpha^{(k)})$

2. until $(\|\nabla f_i(\alpha^{(k)})\| \leq T)$

3. return $\alpha^{(k)}$

... Recently

SGD tends to generalize better
than full / Batch GD.



Strongly Convex

$f(\alpha)$ is str. convex if

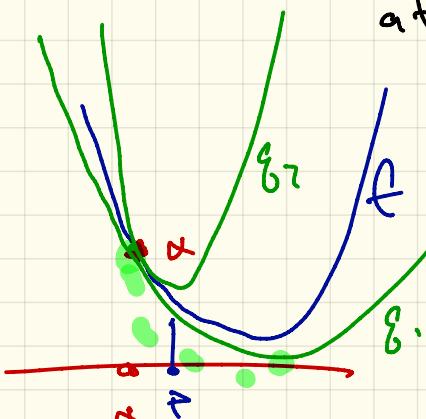
at each $\alpha \in \mathbb{R}^d$ \exists quadratic functions $g_1, g_2 : \mathbb{R}^d \rightarrow \mathbb{R}$

so all $p \in B_r(\alpha)$ have

$$g_1(p) \leq f(p) \leq g_2(p)$$

Lipschitz

$$g_1(\alpha) = f(\alpha) = g_2(\alpha)$$



$$g_1(p) = f(\alpha) + \langle \nabla f(\alpha), p - \alpha \rangle + \frac{n}{2} \|p - \alpha\|^2$$

Decomposable functions

$$f(\alpha) = \sum_{i=1}^n f_i(\alpha)$$

usually each f_i is 1 darts point (x_i, s_i)

Non-decomposable try

$$f(\alpha) = (\alpha_1 + 1 + \alpha_2 \alpha_3)^2 (\alpha_1 - \alpha_2)(\alpha_3^2)$$

