

# Intro to Linear Regression

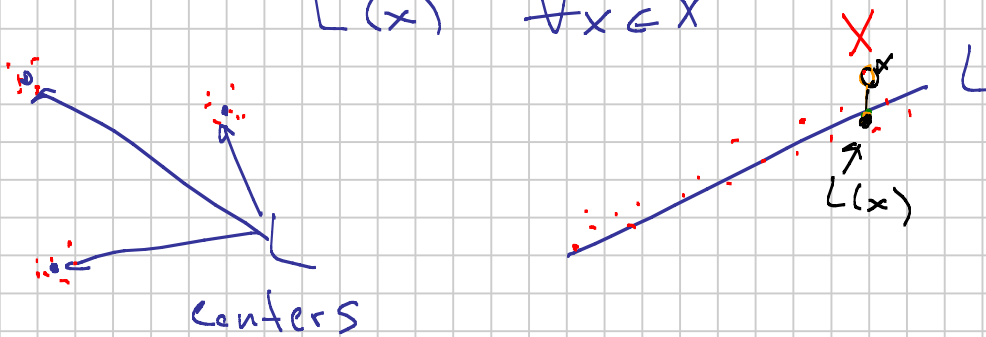
Note Title

2/29/2016

Input Data:  $X$

↳ Simple Pattern  $L$

map  $\mu: X \rightarrow L$   
 $L(x) \quad \forall x \in X$



- Midterm
- Assign #4
- Notes
- Intermediate Report
- Move Office Hours  
Tue @ 2:30-3:30

## Linear Least-Squares Regression

Data  $\rightarrow P \subset \mathbb{R}^2$

$P = (P_x, P_y) \in \mathcal{P}$

$\langle v, u \rangle = \|v\| \cdot \|u\| \cdot \cos(\theta)$   
 $\frac{u \cdot v}{\|v\|}$

Goal: line  $l: y = a x + b$   
 parameters

$P_x = \{P_x \mid P \in \mathcal{P}\}$   
 $P_y = \{P_y \mid P \in \mathcal{P}\}$

$$L_2 \text{ cost} \mid L_2(P, a, b) = \sum_{P \in \mathcal{P}} (P_y - a P_x - b)^2$$

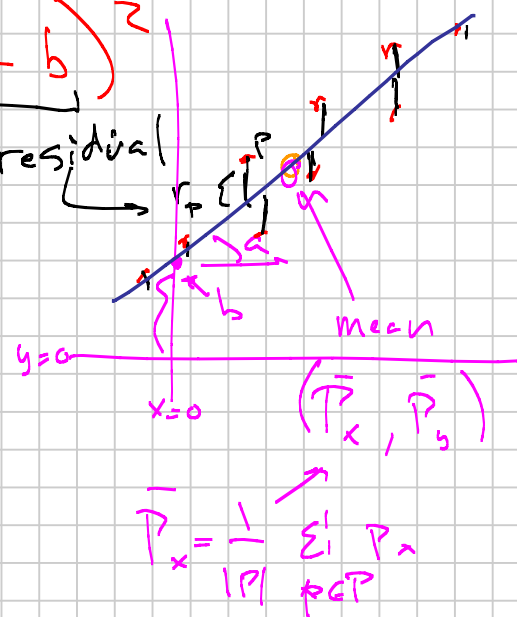
$$\text{Cov}[P_x, P_y] = \frac{1}{n} \sum_{P \in \mathcal{P}} (P_x - \bar{P}_x)(P_y - \bar{P}_y)$$

$$\text{Var}[P_x] = \text{Cov}[P_x, P_x]$$

$$a = \frac{\text{Cov}[P_x, P_y]}{\text{Var}[P_x]} = \frac{\langle P_x, P_y \rangle}{\|P_x\|^2}$$

$$b = \bar{P}_y - a \bar{P}_x$$

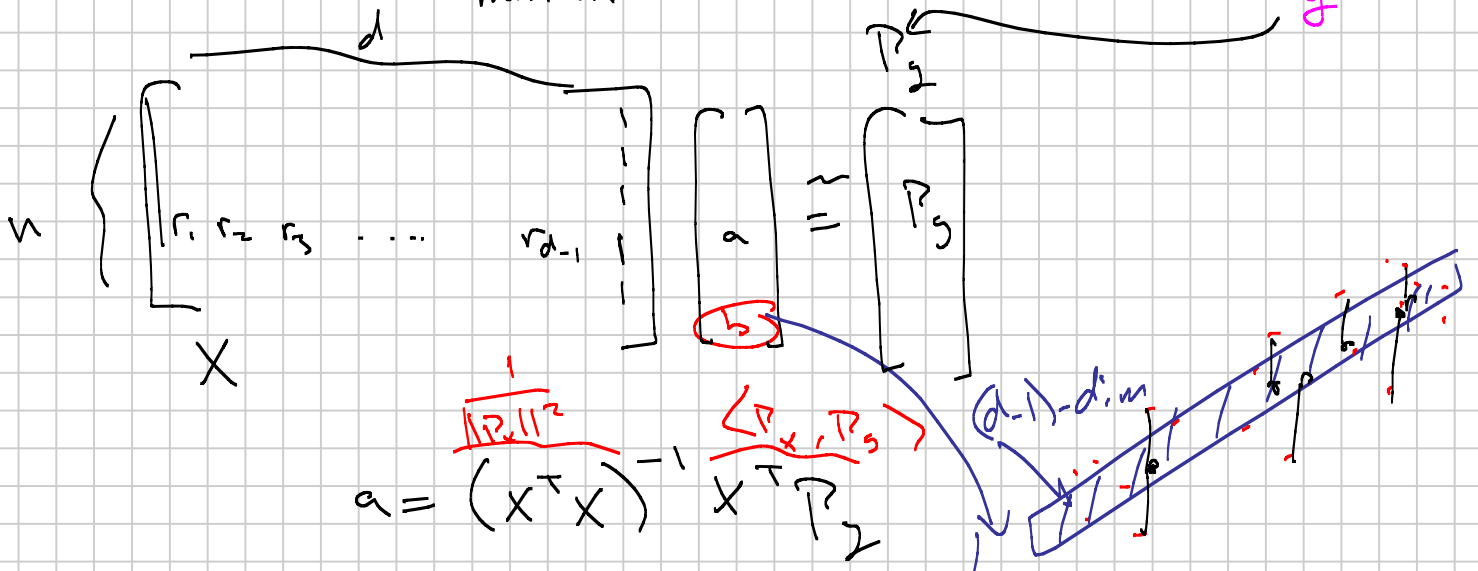
after centering  $y=0$



$$\bar{P}_x = \frac{1}{|P|} \sum_{P \in \mathcal{P}} P_x$$

$P \subset \mathbb{R}^d \rightarrow X$   
 $n \times d$   
 matrix

$P = (r_1, r_2, r_3 \dots r_{d-1}, r_d)$   
 (with a pink 'x' under the first part and a pink 'y' on the right)



$a = (X^T X)^{-1} X^T P_2$

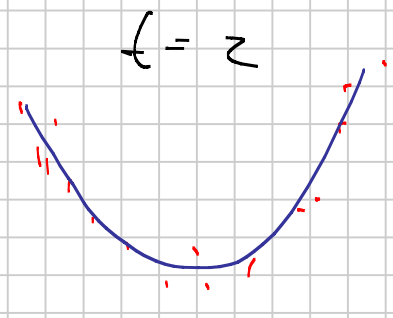
"hat"

$H_x = X(X^T X)^{-1} X^T$   
 $\hat{y} = Xa = H_x y$       $y = P_2$

## Nonlinear (polynomial) LS

fit polynomial degree  $t$

$L: y = a_0 + a_1 x + a_2 x^2 + \dots + a_t x^t$   
 $= \sum_{i=0}^t a_i x^i$



$P_x \rightarrow [1, P_x, P_x^2, P_x^3, \dots, P_x^t]$

"lifting"  
 "linearization"

## Gauss-Markov Thm

LS sol (above) optimal

- • solution 0 expected error  $E[L(x) - x] = 0$
- all errors  $r_p = P_y - L(p_x)$  are not known to be correlated

- Squared Error (Min Variance)

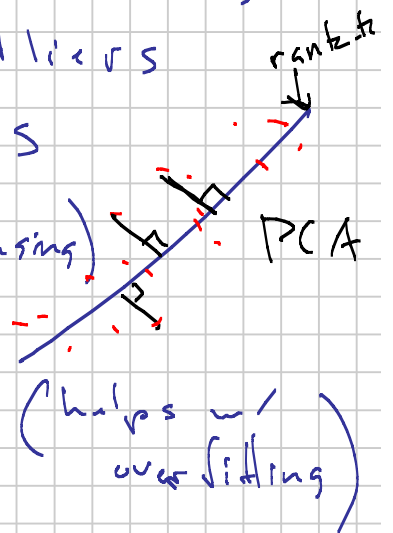
↳ not resistant to outliers

- Vertical Distance Residuals

- What if  $n < d$  (compressed sensing)

- We can add bias

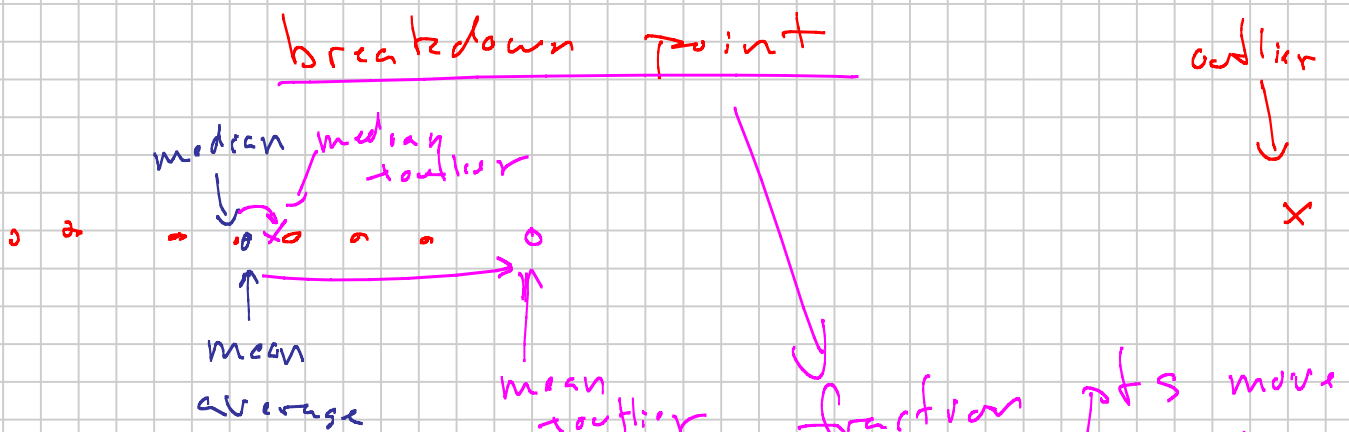
$$\sum_{P \in \mathcal{P}} (P_S - L(P_S))^2 = \text{Var} + \text{Bias}$$



- $(X^T X)^{-1}$  ← expensive ⇒ Matrix Stretching

## Outliers

## Robust (Resistive) Estimator



breakdown pt. mean =  $\frac{1}{n} \rightarrow 0$   
 " " median =  $\frac{1}{2}$

fraction pts move to  $\infty$  and estimator does not move to  $\infty$

## Thiel-Sen Estimator

(Siegel Est. bdppt 0.5)

bdp<sub>pt</sub> = 0.75  $\hat{a} = S_{ij}$

slopes  $S_{ij} = \frac{y_j - y_i}{x_j - x_i}$

$P_x \rightarrow \text{sort } (P_{x_1} \leq P_{x_2} \leq P_{x_3} \leq \dots)$

$a = \text{med}(S_{ij} \mid P_{x_i} \leq P_{x_j})$        $b = \text{med}(\{y_i - a x_i\})$

# Tikhonov Regularization (Ridge Regression)

Assume  $\bar{P}_x = 0$   $\bar{P}_y = 0$  centered.

Goal  $L_{2,s}(P, a) = \sum_{P \in \mathcal{P}} \underbrace{(P_y - a P_x)^2}_{\text{"variance"}} + \underbrace{s a^2}_{\text{regularizer "bias"}}$

Equivalent Formulation

$$L_2^t(P, a) = \sum_{P \in \mathcal{P}} (P_y - a P_x)^2 \quad \text{s.t. } a^2 \leq t$$

$$\hat{a}_s = \frac{\langle P_x, P_y \rangle}{\|P_x\|^2 + s^2} = (X^T X + s^2 I)^{-1} X^T P_y$$

$\exists$  some parameter  $s$  s.t.

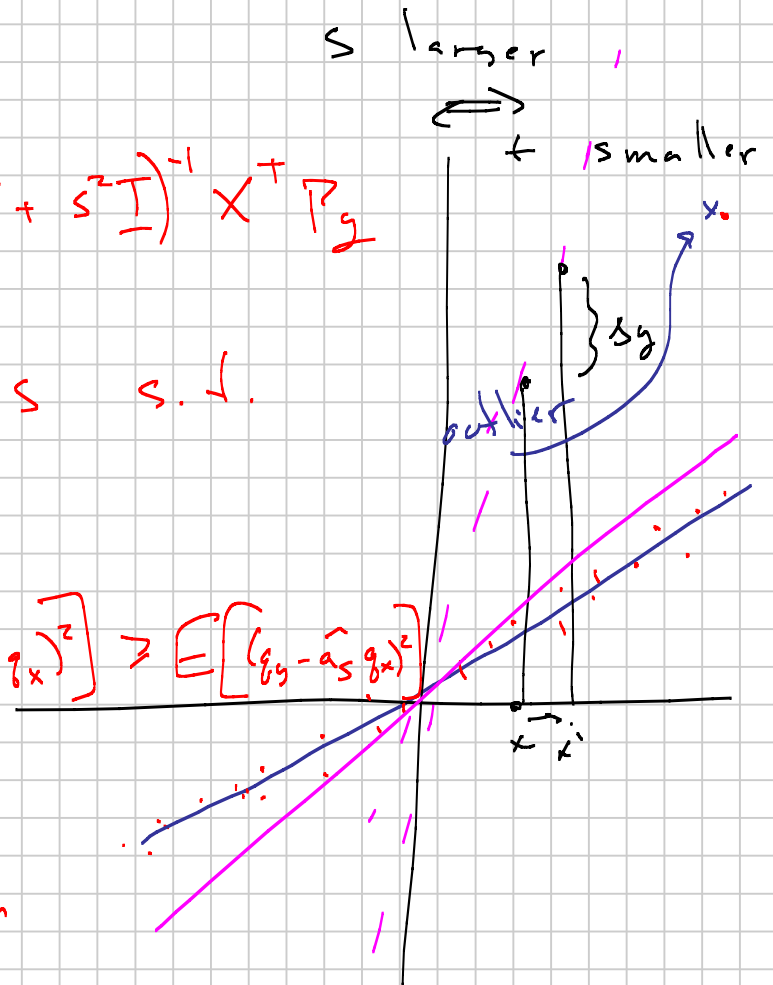
$$P \sim \mathcal{D}(a) \rightarrow \hat{a}_s$$

$$g \sim \mathcal{D}(a)$$

$$\rightarrow E[(g_y - \hat{a}_s g_x)^2] \geq E[(g_y - a g_x)^2]$$

How to choose  $s$ ?

$\rightarrow$  Cross-Validation



# Lasso (Basis Pursuit)

$$L_{1,s}(P, a) = \sum_{P \in \mathcal{P}} (P_y - a P_x)^2 + s |a|$$

$$L_1^t(P, a) = \sum_{P \in \mathcal{P}} (P_y - a P_x)^2 \quad \text{s.t. } |a| \leq t$$