

Distributed Trajectory Similarity Search

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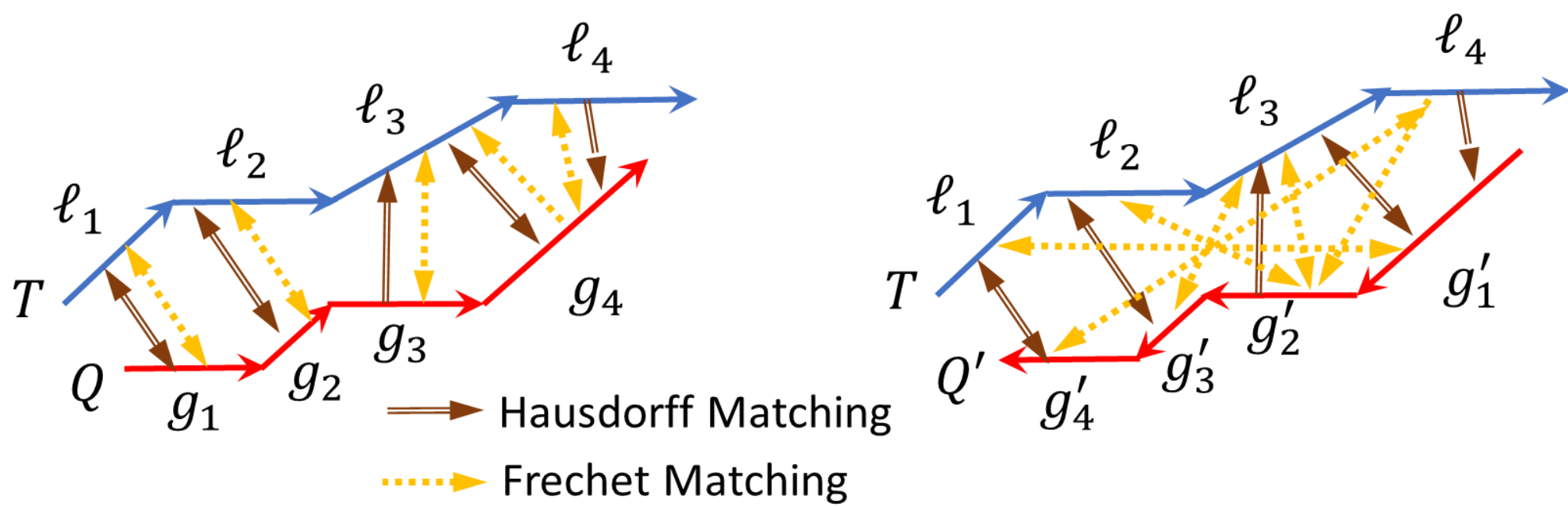
Motivation

Huge amount of trajectory data are being generated everyday.
 Widely used in traffic analysis, transportation planning.
 Classic problem: find **'similar' trajectories**.
 Require distributed solutions to **scale out**.

Trajectory Similarity Search

k nearest neighbor query over trajectories under a specific distance metric D .
Not yet studied under a distributed environment.

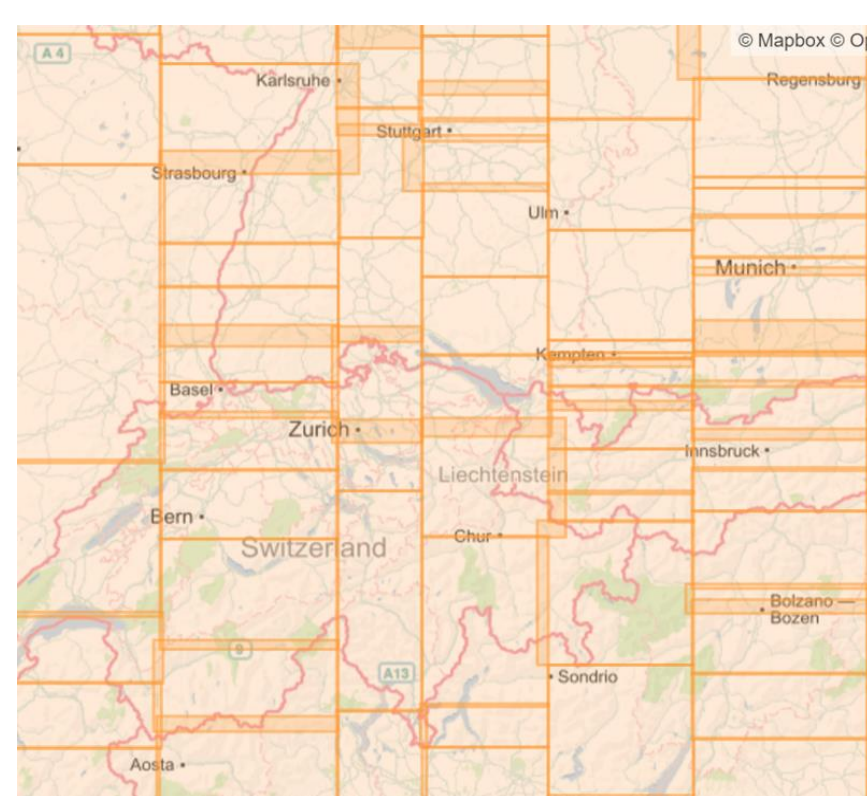
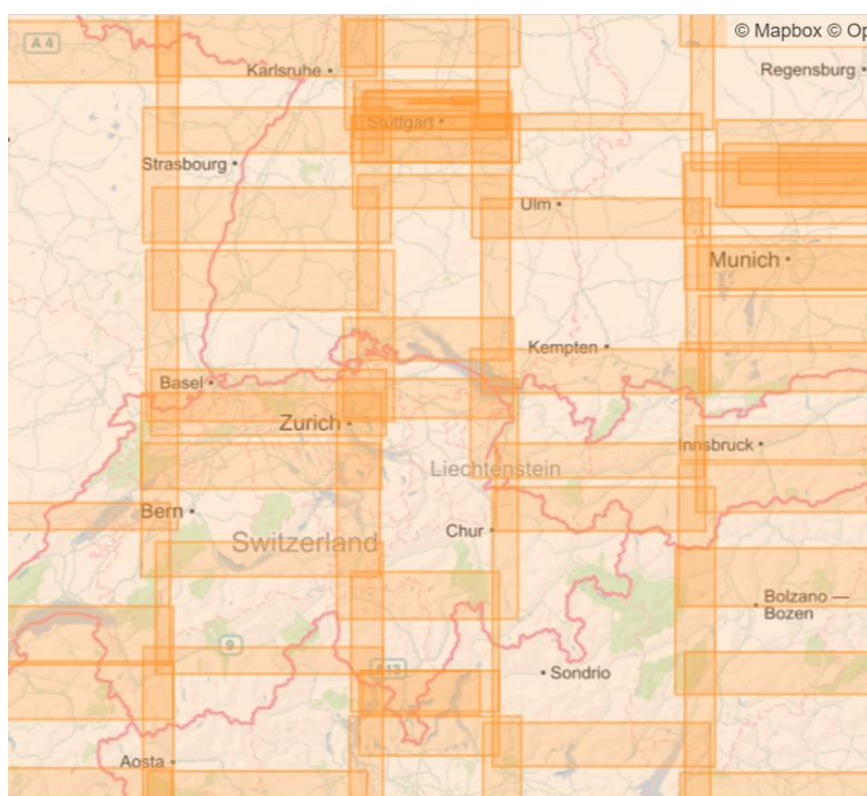
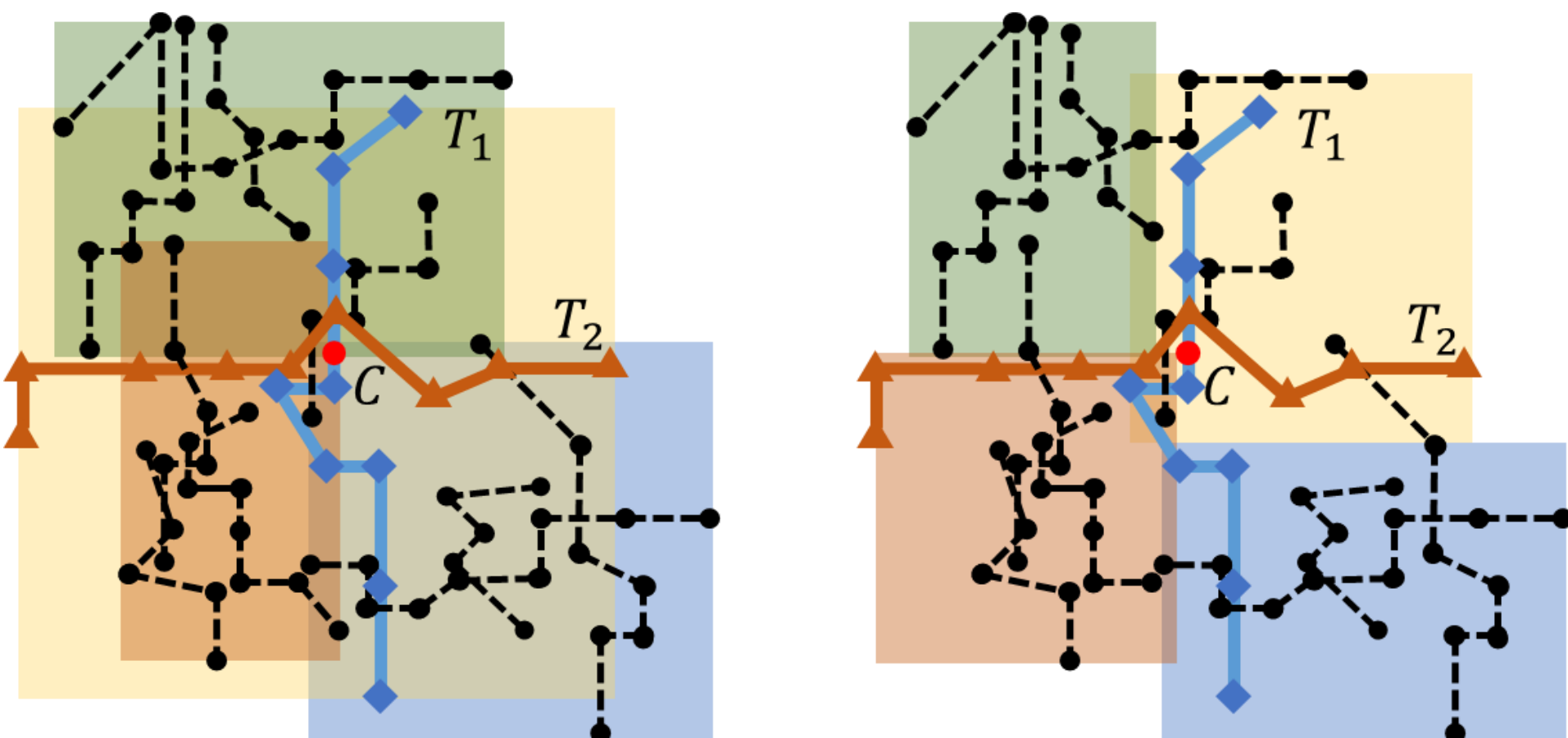
Different metrics: Hausdorff distance vs. Frechet distance



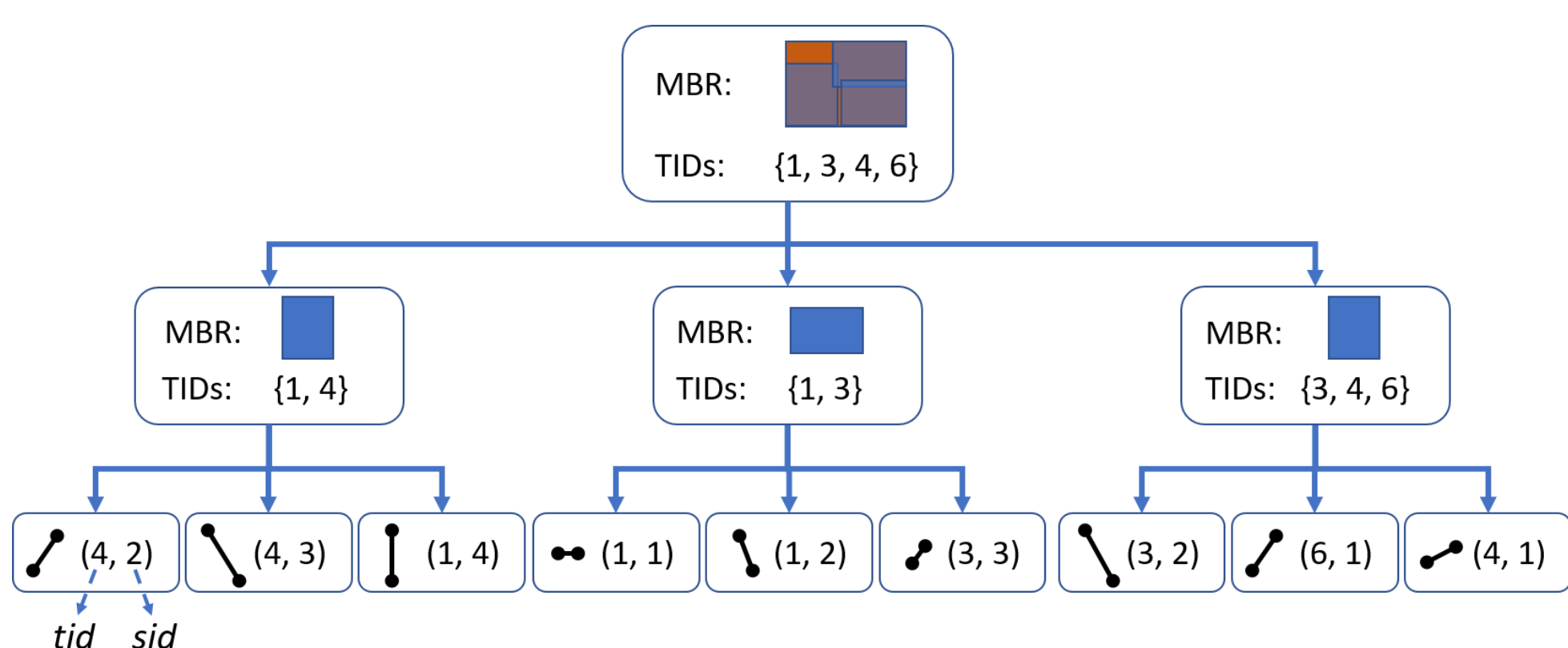
Segment-based vs. Trajectory-based Indexing

Partition **trajectories** as individual objects

Partition all **segments** in trajectories

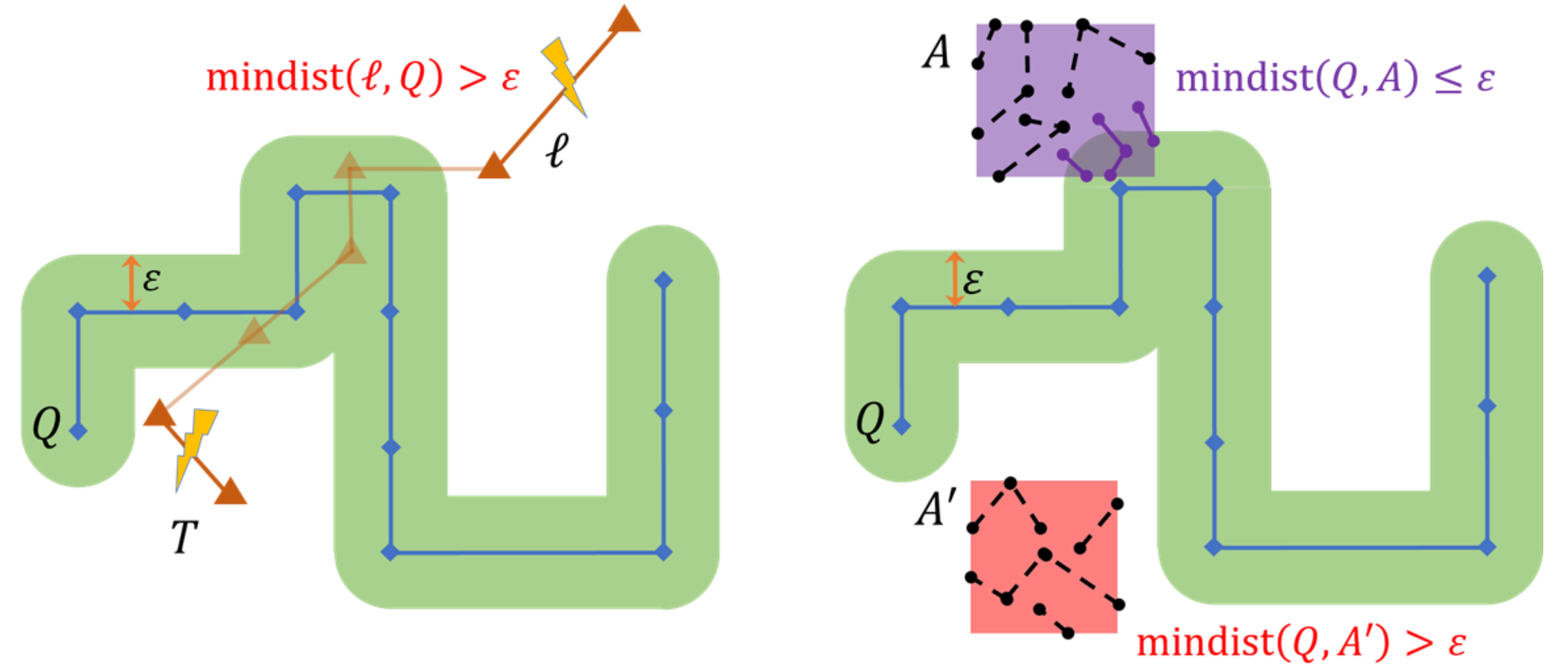


Customized R-Tree Local Index



Pruning Theorem

Given a distance threshold $\epsilon > 0$, and two trajectories Q and T .
 If there exists a segment $\ell_i \in T$ such that $\text{mindist}(\ell_i, Q) > \epsilon$,
 then we have $D_H(Q, T) > \epsilon$ and $D_F(Q, T) > \epsilon$



Search Procedure

Step 1: Pruning Bound Selection

Find a safe pruning bound ϵ covering at least k data trajectories.
 Sample $c \cdot k$ trajectories passing similar regions as the query trajectory.
 Find the k -th closest distance as the pruning bound ϵ .
 Theory beneath: quantile estimation based on samples.

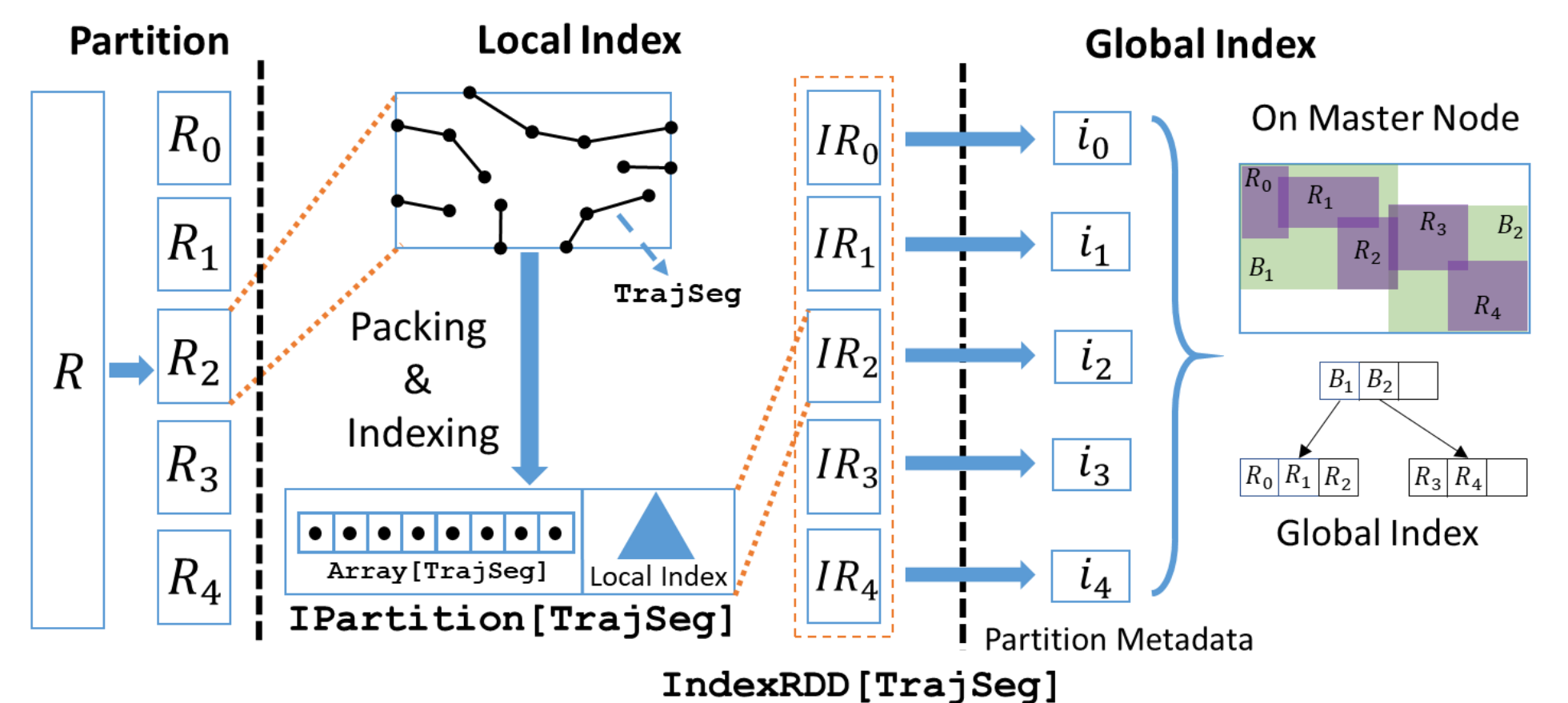
Step 2: Index-based Pruning

Utilize the distributed index to find the set of trajectory IDs can be safely pruned by ϵ .

Step 3: Finalizing Results

Rebuild all candidate trajectories, then launch a distributed top-K.

Two Level Indexing in Apache Spark



Design Choice and Optimization

Concise Data Structure for TID sets in customized R-Trees.
Roaring Bitmap: a *concise and flexible* compressed bitmap

Dual Indexing Strategy.

Keep **another data copy** organized in trajectory objects.
 Eliminate the procedure of regrouping candidate trajectories.

Experiment Results

